Intelligent Hearing Aid Project

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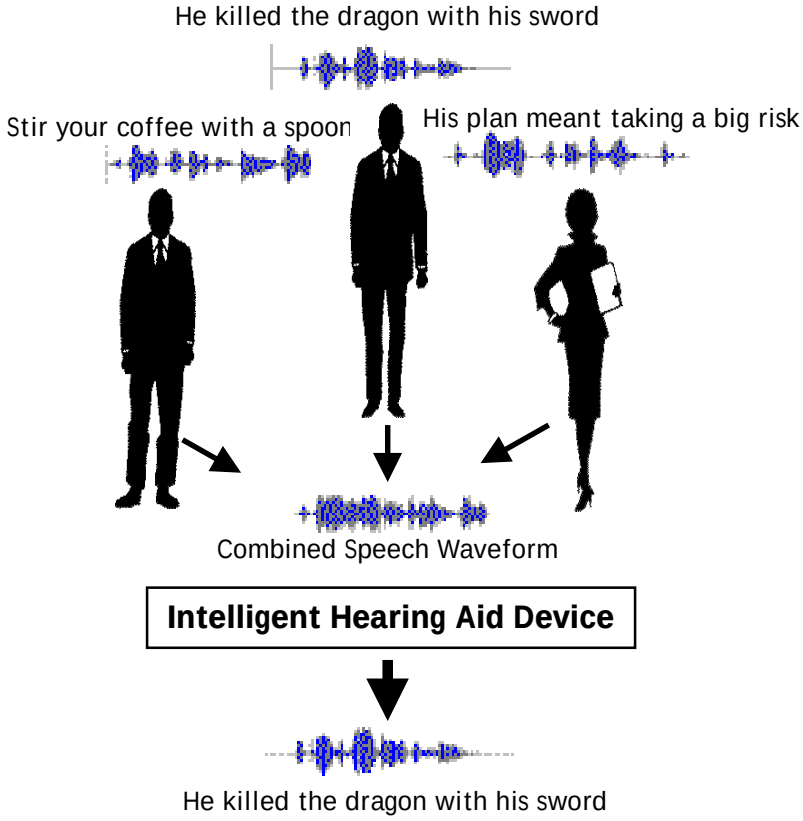


Goal:

Develop high performance auditory processors which can effectively extract a desired speech signal in the presence of multiple competing sounds.

Report Documentation Page

Form Approved
OMB No. 0704-0188

1. REPORT DATE	2. REPORT TYPE	3. DATES COVERED
24 AUG 1999	**N/A**	**-**

4. TITLE AND SUBTITLE	5a. CONTRACT NUMBER
Intelligent Hearing Aid Project	5b. GRANT NUMBER
	5c. PROGRAM ELEMENT NUMBER
6. AUTHOR(S)	5d. PROJECT NUMBER
	5e. TASK NUMBER
	5f. WORK UNIT NUMBER
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) **Beckman Institute**	8. PERFORMING ORGANIZATION REPORT NUMBER
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES)	10. SPONSOR/MONITOR'S ACRONYM(S)
	11. SPONSOR/MONITOR'S REPORT NUMBER(S)

12. DISTRIBUTION/AVAILABILITY STATEMENT
Approved for public release, distribution unlimited

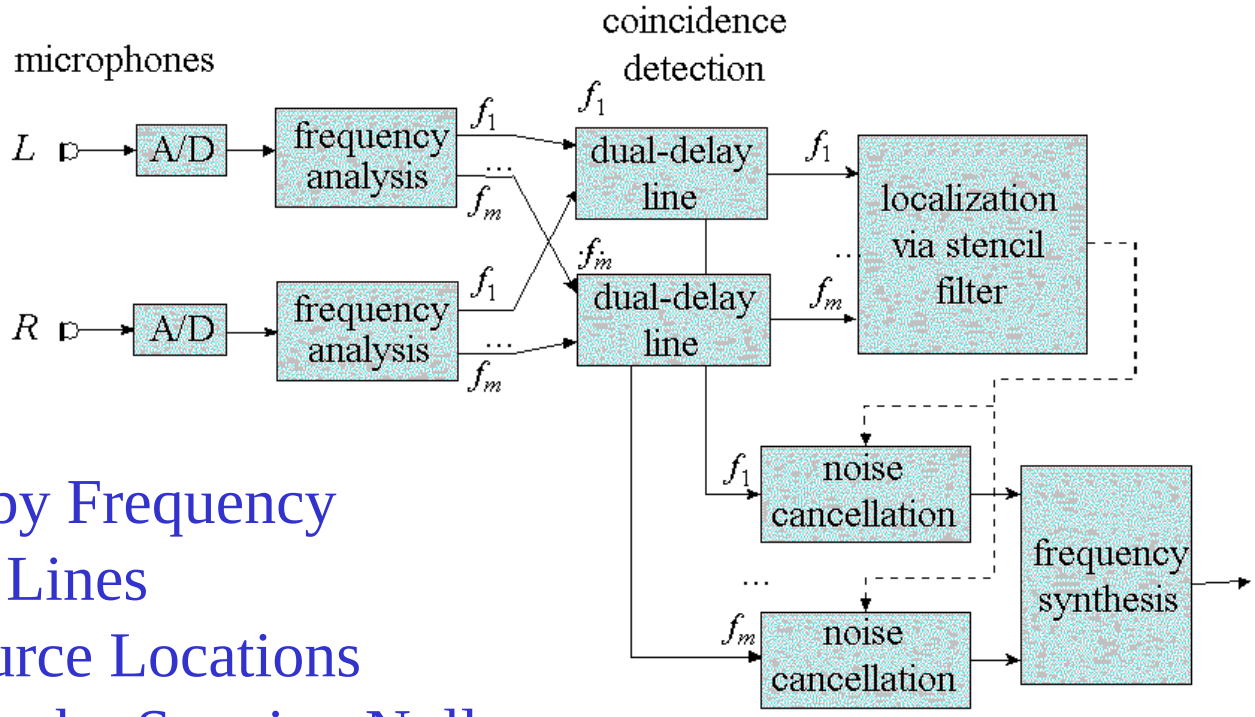
13. SUPPLEMENTARY NOTES
DARPA, Air-Coupled Acoustic Microsensors Workshop held on August 24 and 25, 1999 in Crystal City, VA., The original document contains color images.

14. ABSTRACT

15. SUBJECT TERMS

16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT	18. NUMBER OF PAGES	19a. NAME OF RESPONSIBLE PERSON
a. REPORT **unclassified**	b. ABSTRACT **unclassified**	c. THIS PAGE **unclassified**	**UU**	**7**	

Algorithm 1:
Localization and Cancellation



- Separation by Frequency
- Dual Delay Lines
- Identify Source Locations
- Cancel Noise by Steering Nulls

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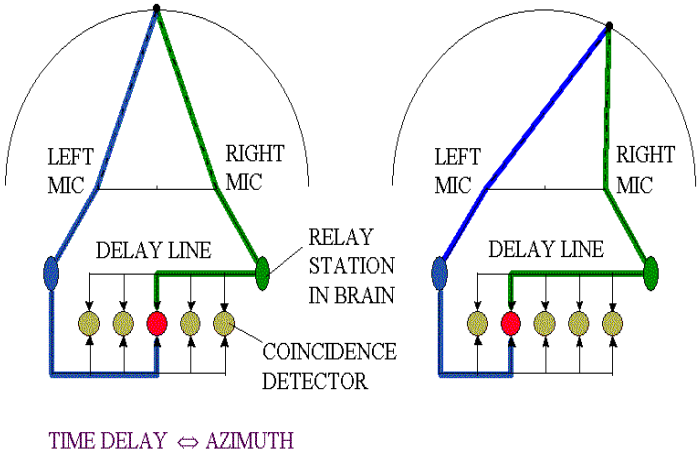
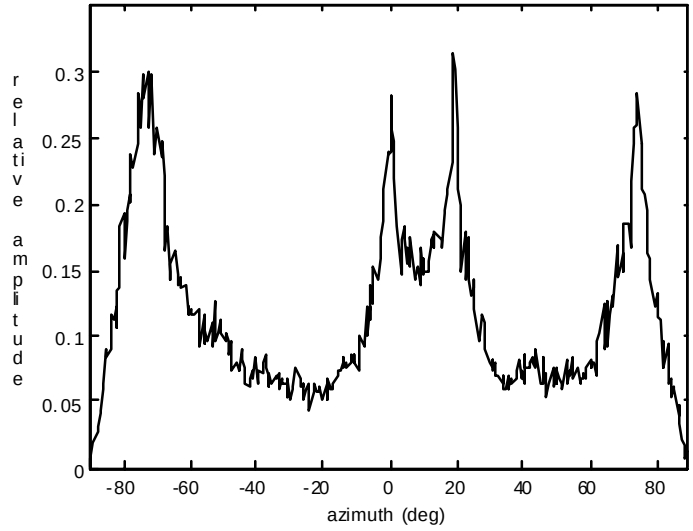
Algorithm 1:
Localization and Cancellation





Localization in the Brain

Localization by Computer
(measure of coincidence vs. azimuth)

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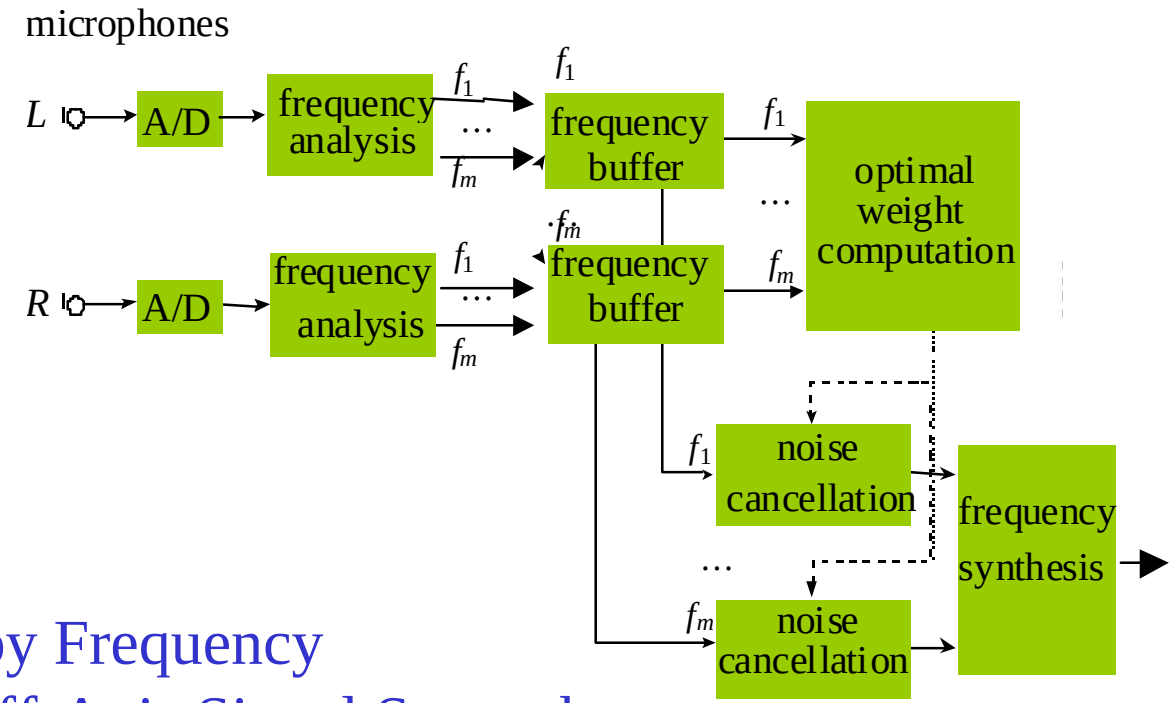
Algorithm 2:
Minimum Variance Cancellation



- Separation by Frequency
- Minimize Off-Axis Signal Strength

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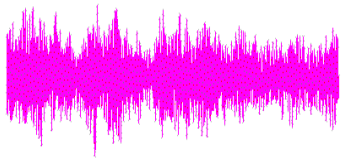
Experimental Examples

The old train was powered by steam

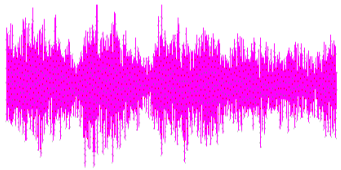
Target @ 0°

Twelve talker babble

Interferor @ 30°



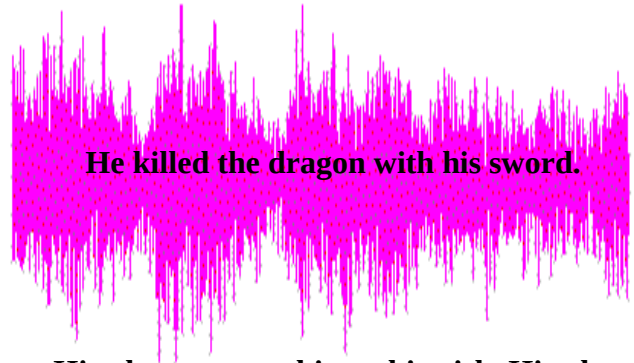
Combined Waveform



Reconstructed Waveform

Stir your coffee with a spoon. Stir your

Interferor @ 65°

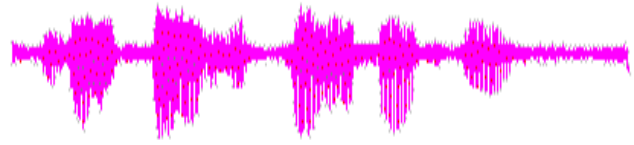


Target @ 0°

His plan meant taking a big risk. His pl

Interferor @ 22°

Combined Waveform



Reconstructed Waveform

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Experimental Summary

(ALGORITHM 2)

Expmt #	Position Attenuation	Position Attenuation	Position Attenuation	Position Attenuation	Average Gain
1	-75° 4.8 dB	Target: 0° 0.6 dB	20° 4.1 dB	75° 2.1 dB	6.2 dB
2	30° 6.3 dB	-45° 4.2 dB	60° 3.1 dB	Target: -10° 0.6 dB	6.7 dB
3	Target: 10° 1.1 dB	-80° 3.9 dB	-50° 2.9 dB	45° 2.7 dB	4.6 dB
4	-30° 6.3 dB	15° 0.9 dB	Target: 5° 0.9 dB	-60° 3.6 dB	5.3 dB
5	-25° 5.7 dB	Target: 25° 0.7 dB	-70° 4.3 dB	80° 2.9 dB	6.3 dB

Recordings made in a Conference Room

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Current and Future Work

- **Real-Time Implementation**
- **Microphone Compensation**
- **Dereverberation**

Thanks to Dr. Chen Liu (now at Motorola), Dr. Marc Goeygou (now at U. Lisle) and grad students Mike Lockwood and Mark Elledge

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